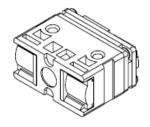


MT10

(3.3V Linear Image Barcode Scan Engine)

Integration Guide



Version 1.6 DATE: 2018/3/15



MT10 Linear Image Barcode Scan Engine, Integration Guide, V1.6

TABLE OF CONTENTS	
1. INTRODUCTION	1
1-1. MT10 Block Diagram	1
1-2. Electric Interface	2
1-2-1. Pin Assignment	2
1-2-2. Electric Characteristics	5
1-2-3. Flex Cable	5
1-3. Operational Timing	6
1-3-1. Power Up	6
1-3-2. Sleep (Idle) Mode	6
1-3-3. Decode Timing	6
1-3-4. Summary of Operation Timings	7
2. SPECIFICATIONS	7
2-1. Introduction	7
2-2. Technical Specifications	7
2-3. Interface	9
2-3-1. UART Interface	9
2-3-2. USB Interface	.10
2-4. Operation Method	.11
2-5. Mechanical Dimension	.11
2-6. Scanning Range	.12
2-7. Pitch Angle, Roll Angle and Skew Angle	. 13
2-8. Specular Dead Zone	. 14
2-9. Curvature Degree	. 15
2-10. Flex Cable Specification	15
2-11. Connector Specification	.16
3. INSTALLATION	. 17
3-1. Electrostatic Discharge Cautions	.17
3-2. Mechanical Dimension	17
3-3. Window Materials	.18
3-4. Window Specifications	. 19
3-5. Window Care	. 21
4. REGULATIONS	21
5. DEVELOPMENT KIT	. 22
6. SLEEP (IDLE) MODE	. 23
7. PARAMETER SETUP	.24
VEDEION LIETORY	25



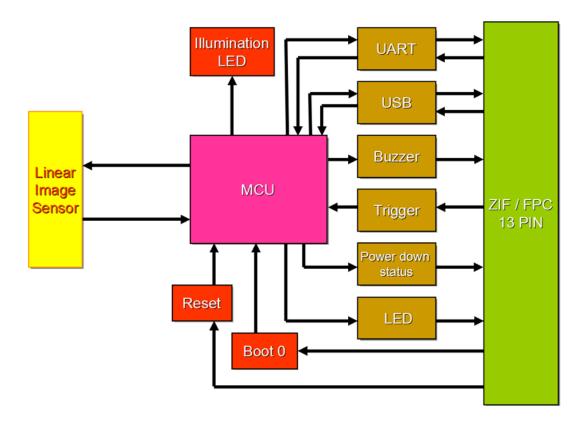
1. INTRODUCTION

The MT10 Linear Image Barcode Scan Engine is designed for 1D barcode middle range reading, and high performance barcode scanning with optimal performance and easy integration. MT10 is ideal for integration into data terminals and other small mobile devices.

The MT10 consists of 2 illumination LEDs, a high-quality linear image sensor and a microprocessor that contains powerful firmware to control all aspects of operations and enable communication with the host system over the standard set of communication interfaces.

Two interfaces, UART & USB, are available. UART interface communicates with the host system over TTL-level RS232 communication; USB interface emulates a USB Keyboard device and communicates with the host system over USB.

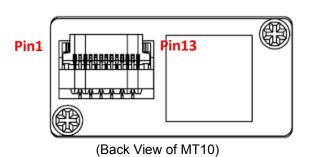
1-1. MT10 Block Diagram

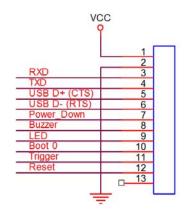




1-2. Electric Interface

1-2-1. Pin Assignment





Pin#	UART	USB	I/O	Description	Schematic Example
1	VCC	VCC		Supply voltage input. Must always be connected to a 3.3V power supply.	+3V3 <<
2	GND	GND		Power and signal ground.	<u></u>
3	RXD		Input	UART TTL data input.	R\$232 IC TMD
4	TXD		Output	UART TTL data output.	RS232 IC TXD



MT10	Linear	Image	Scan	Fnaine	Integration	Guide	V1 6
101110	Liiicai	mage	Ocari	Lingino,	micqiallon	Guide,	v 1.0

Pin#	UART	USB	I/O	Description	Schematic Example
5	CTS		Input	When handshaking is enabled, host authorizes MT10 to transmit data on TXD line.	RS232 IC TXD
		USB D+	Bidirectional	Differential Signal Transmission	
6	RTS		Output	When handshaking is enabled, MT10 requests permission from host to transmit data on TXD line.	R\$232 IC TXD
		USB D-	Bidirectional	Differential Signal Transmission	
7	Power down	Power down	Output	Active high, it indicates that the MT10 is in Sleep Mode (See Chapter 6 for details)	
8	Buzzer	Buzzer	Output	Active high: Power-Up or a successful barcode decoded. PWM controlled signal can be used to drive an external buzzer for a successful barcode decoded (Good Read).	HD1



MT10 Linear Image Scan Engine, Integration Guide, V1.6

Pin#	UART	USB	I/O	Description	Schematic Example
9	LED	LED	Output	Active high, it indicates the status of Power-Up or a successful barcode decoded (Good Read).	VCC LED1 GREEN R11 330R Q4 2N3904
10	Boot 0	Boot 0	Input	Reserved for production only.	
11	Trigger	Trigger	Input	High: Power-up/Standby Low: Scanning Operation *Note: 1. Scanning operation continues until a barcode is successfully decoded or the trigger is released (pull high). To proceed to the next scanning operation, release (pull high) first and press (pull low) the trigger again. 2. Pull low at power-up will prompt the scan engine into firmware update mode.	3.3V ———————————————————————————————————
12	Reset	Reset	Input	Reserved for production only.	



1-2-2. Electric Characteristics

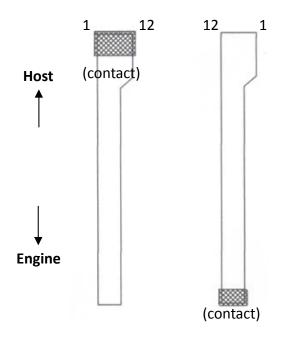
Symbol	Ratings	Min	Max	Unit
V _{IH}	Input high level	2.0	3.6	٧
V _{IL} Input low level		0	1.1	V
V _{OH}	Output high level	2.9		V
V _{oL} Output low level			0.4	V
∆V _{DDx}	Variations between different V _{DD}		50	mV
	power pins		00	111 V

*Note:

- 1. Power Supply: **V**_{DD}=3.3
- 2. Exposure to maximum rating conditions for extended periods may affect device reliability.

1-2-3. Flex Cable

The flex cable is used to connect MT10 to the host side. There are 13 pins on the MT10 (engine) side and 12 pins on the host side. Please see 2-10 for more details of flex cable.



Flex cable (P/N: 6351-0501113)					
Pin#	Pin Assignment To Host				
1	VCC				
2	GND				
3	RXD				
4	TXD				
5	USB D+ / CTS				
6	USB D- / RTS				
7	Power Down				
8	Buzzer				
9	LED				
10	Boot0				
11	Trigger				
12	Reset				

*Note: Conforms to MARSON MT700/MT710D's pin assignment.



1-3. Operational Timing

This chapter describes the timing associated with the various operating modes of the MT10 including Power Up, Sleep Mode, and Decode Timing.

1-3-1. Power Up

When power is initially applied, the MT10 is activated and begins the process of initialization. Once initialization (duration \leq 10mS) is completed, the MT10 enters **Standby Mode** and is ready for barcode scanning.

1-3-2. Sleep (Idle) Mode

The MT10 will enter **Sleep (Idle) Mode** and output a Power Down signal (Active high) after a programmable time period has elapsed without any activity. Please see Chapter 6 for more details about Sleep Mode.

1-3-3. Decode Timing

In **Standby Mode**, The MT10 is activated by the Trigger signal which MUST be kept low for at least 20 ms until the successful scan is achieved, as indicated by the Buzzer/LED signals.

In **Sleep Mode**, the MT10 can be waken up by the Trigger signal which MUST be kept low for at least 20 mS until the successful scan is achieved, as indicated by the Buzzer/LED signal.

The total scan and decode time is approximately equal to the time from the Trigger signal going low to the Buzzer/LED signal going high. This time will vary slightly based on several factors including barcode quality, barcode type and the distance between MT10 and the barcode scanned.

Upon a successful scan, the MT10 outputs the Buzzer/LED signal and keeps this signal for the duration of the transmission of the data decoded to the host side. The duration is about 75 ms.

Therefore, the total duration of a typical scanning operation (from Trigger turning low to the end of Buzzer PWM signal) is also approximately 120mS.



1-3-4. Summary of Operation Timings

- 1. The maximum duration of initialization is 10mS.
- 2. The maximum duration of scanning operation in Standby Mode is 120mS.
- 3. The minimum duration of waking up MT10 from Sleep Mode by Trigger signal is about 2 ms.
- 4. The maximum duration of waking up MT10 from Sleep Mode by Trigger signal and completing decode (when barcode is within optimal focus) is about 120ms

2. SPECIFICATIONS

2-1. Introduction

This chapter provides technical specifications of the MT10 scan engine. Operating method, scanning range and scan angle are also presented.

2-2. Technical Specifications

Optic & Performance				
Light Source	625nm visible red LED			
Sensor	Linear Image Sensor			
Scan Rate	650 Scans/ sec			
Resolution	4mil/ 0.1mm			
Scan Angle	41°			
Print Contrast Ratio	30%			
Width of Field	140mm (13Mil Code39)			
	4 Mil Code39: 45 ~ 70mm (4 digits)			
Donth Of Field	5 Mil Code39: 40 ~ 95mm (4 digits)			
Depth Of Field (Environment: 800 lux)	10 Mil Code39: 35 ~ 195mm (4 digits)			
(Liiviioiiiileiit. 600 lux)	15 Mil Code39: 45 ~ 275mm (4 digits)			
	13 Mil UPC/ EAN: 40 ~ 230mm (13 digits)			
Physical Characterist	ics			
Dimension	W14 x L11.9 x H7 mm			
Weight	1g			
Color	Black			
Material	PC			
Cable	13pin to 12pin flex cable			



MT10 Linear Image Scan Engine, Integration Guide, V1.6

Electrical	_		
Operation Voltage	3.3VDC±0.15VDC		
Working Current	< 75mA (UART) ; < 85mA (USB)		
Standby Current	< 35mA (UART) ; < 45mA (USB)		
Idle Current (Sleep Mode)	< 300uA (UART) ; < 500uA (USB)		
Surge Current	< 500 mA		
Connectivity			
Interface	UART (TTL-level RS232)		
	USB (HID Keyboard)		
User Environment			
Operating Temperature	0°C ~ 50°C		
Storage Temperature	-20°C ~ 60°C		
Humidity	0% ~ 95%RH (Non-condensing)		
Drop Durability	1.5M ()		
Ambient Light	100,000 Lux (Sunlight)		
Symbologies	UPC-A/ UPC-E EAN-8/ EAN-13 Matrix 2 of 5 China Postal Code (Toshiba Code) Industrial 2 of 5 Interleaved 2 of 5 Standard 2 of 5 (IATA Code) Codabar Code 11 Code 32 Standard Code 39 Full ASCII Code 39 Code 93 Code 128 EAN/ UCC 128 MSI Plessey Code UK Plessey Code Telepen Code GS1 Databar		
Regulatory			



MT10 Linear Image Scan Engine, Integration Guide, V1.6

ESD	Functional after 4KV contact, 8KV air discharge (it requires housing that is designed for ESD protection and stray from electric fields.)		
EMC	FCC – Part15 Subpart B (Class B)		
EMC	CE – EN55022, EN55024		
Safety Approval	IEC 62471 (Exempt Group)		
Environmental	WEEE, RoHS 2.0		

2-3. Interface

2-3-1. UART Interface

Below default values of communication parameters apply to both Standard mode and Command mode firmware.

Baud rate: 9600 Data Bits: 8 Parity: None

Stop Bit: 1

Handshaking: None

Flow Control Timeout: None

ACK/NAK: OFF

BCC: OFF

A. Standard Mode

Firmware version: SM3-d-x.xx (MT10 P/N: 110P-A000000)

Characteristics:

- (1) Configurable by scanning configuration barcodes or Ez Utility® (a PC-based software utility, available for download at www.marson.com.tw)
- (2) Supports hardware trigger only

Interface Configuration Barcode:

. COO2\$



UART

Scanning above barcode will set your MT10 to UART interface.



B. Command Mode

Firmware version: SM3-d-x.xx.CMD (MT10 P/N: 110P-4000000)

Characteristics:

- (1) Configurable by commands sent from host or BEO® (a PC-based software utility, available for download at www.marson.com.tw)
- (2) Supports both hardware and software triggers

Interface Configuration Barcode:

Not supported.

2-3-2. USB Interface

Firmware version: SM3-d-x.xx (MT10 P/N: 110P-A000000)

Characteristics:

- Configurable by scanning configuration barcodes or Ez Utility[®] (a PC-based software utility, available for download at www.marson.com.tw)
- (2) Supports hardware trigger only
- (3) Emulates a USB Keyboard device

Interface Configuration Barcode:

. coos\$



USB HID

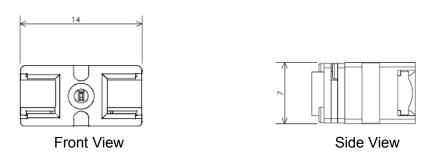
Scanning above barcode will set your MT10 to USB interface.

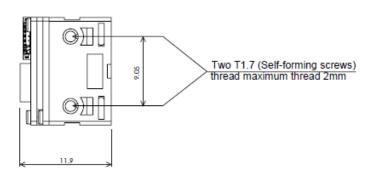


2-4. Operation Method

- At power-up, the MT10 sends the Power-Up signals over Buzzer and LED pins as an indication that the MT10 enters into **Standby Mode** and is ready for operation.
- 2. Once the MT10 triggered by either hardware or software method, it will emit a narrow, horizontal slab of light which is aligned with the sensor's field of view.
- 3. The linear image sensor captures the linear image of barcode and produces an analog waveform, which is sampled and analyzed by the decoder firmware running on the MT10.
- Upon a successful barcode decoded, the MT10 turns off the illumination LEDs, sends the Good Read signals over Buzzer and LED pins and transmits the decoded data to the host.
- 5. The MT10 may enter into **Sleep Mode** (Please see Chapter 6 for more details) after a period of inactivity in order to reduce power consumption.

2-5. Mechanical Dimension

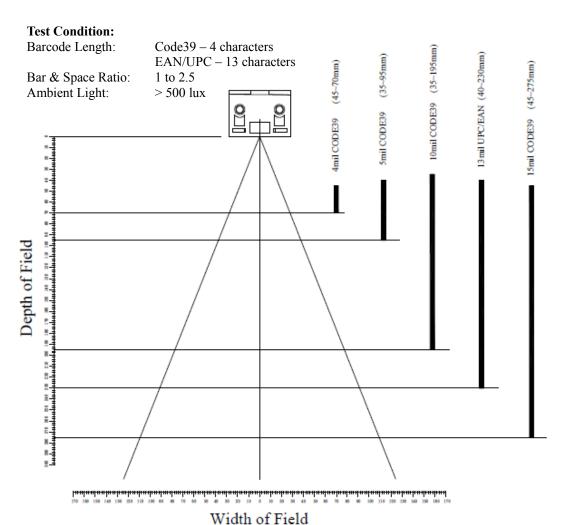




Top View



2-6. Scanning Range



Minimum & Maximum Scan Distance

Symbology	Resolution	Distance	No. of Encoded Characters
	4 Mil	45 ~ 70 mm	
Standard	5 Mil	35 ~ 95 mm	4 char.
Code 39 (w/o checksum)	10 Mil	35 ~ 195 mm	4 Cilai.
,	15 Mil	45 ~ 275 mm	
EAN 13	13 Mil	40 ~ 230 mm	13 char.

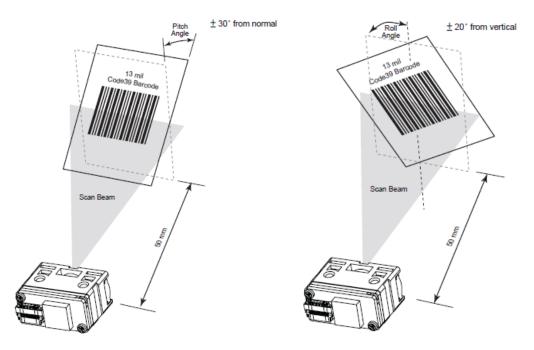
Maximum Scan Width

Symbology	Resolution	Barcode Length	No. of Encoded Characters
Standard			
Code 39	13 mil	140 mm	27 char.
(w/o checksum)			



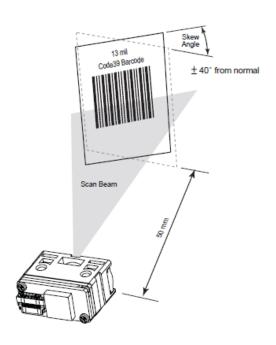
2-7. Pitch Angle, Roll Angle and Skew Angle

Be aware of the tolerance for the pitch, roll and skew angle of bar code you are trying to scan.



Pitch Angle: ± 30°

Roll Angle: ± 20°

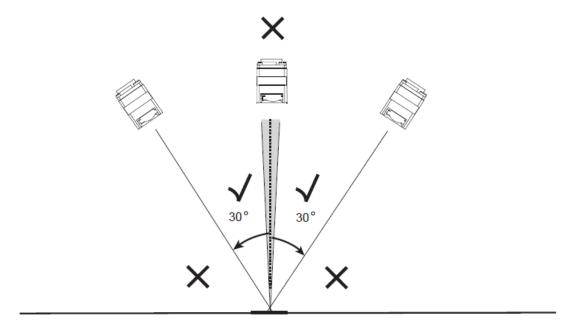


Skew Angle: ± 40°



2-8. Specular Dead Zone

Do not place the MT10 directly over the barcode. The light reflecting directly back into the MT10 from the barcode is known as specular reflection, which can make decoding difficult. The specular dead zone of MT10 is up to 5° depending on target distance and substrate glossiness.

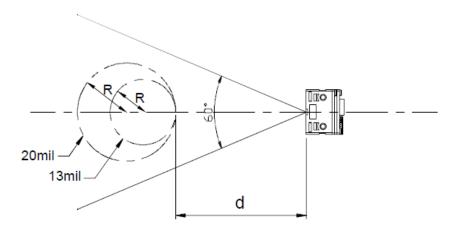


Specular Dead Zone: ± 5°



2-9. Curvature Degree

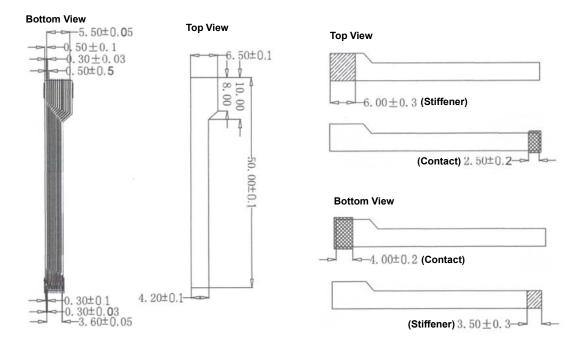
The curvature degree of a scanned barcode is specified as below:



Barcode	Code 39 (L=32 mm) Code 39 (L=43 mm)			
Resolution	13 mil (0.33 mm) 20 mil (0.51 mm)			
R	$R \ge 15 \text{ mm}$ $R \ge 20 \text{ mm}$			
d	40 mm			
PCS	0.9 (printed on photographic paper)			

2-10. Flex Cable Specification

Below is the drawing of the flat cable(P/N: 6351-0501113) that comes with MT10.

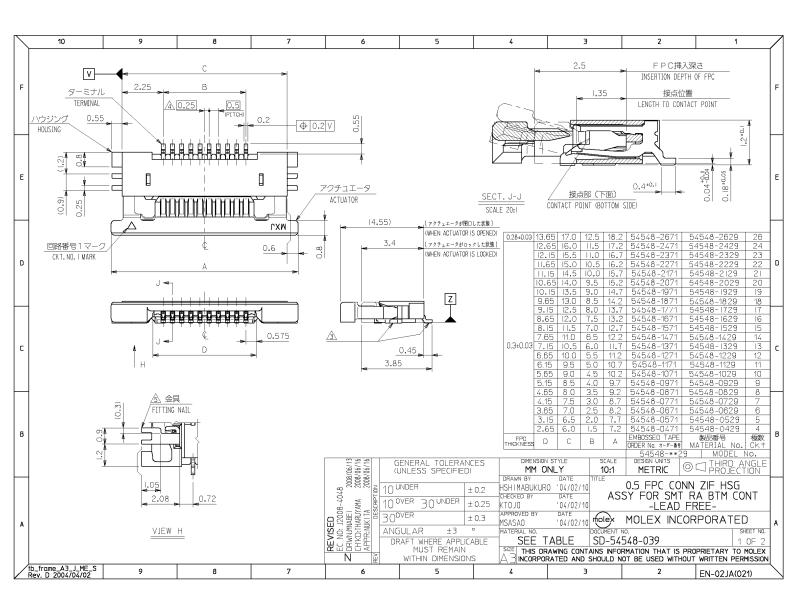




MT10 Linear Image Scan Engine, Integration Guide, V1.6

2-11. Connector Specification

12-pin Molex® FPC Connector (Molex P/N: 54548-1229), to be installed on Host side.





3. INSTALLATION

The MT10 scan engine is designed specifically for integration into customer's housing for OEM applications. However, the MT10's performance will be adversely affected or permanently damaged when mounted into an unsuitable enclosure.

Warning: The limited warranty is void if the following recommendations are not adhered to when mounting the MT10.

3-1. Electrostatic Discharge Cautions

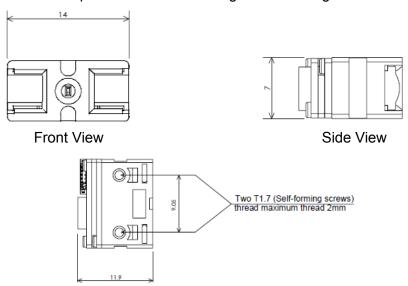
All MT10s are shipped in ESD protective packaging due to the sensitive nature of the exposed electrical components.

- 1. ALWAYS use grounding wrist straps and a grounded work area when unpacking and handling the MT10.
- 2. Mount the MT10 in a housing that is designed for ESD protection and stray electric fields.

3-2. Mechanical Dimension

When securing the MT10 by utilizing the self-forming screws:

- 1. Leave sufficient space to accommodate the maximum size of the MT10.
- 2. Do not exceed 1kg-cm (0.86 lb-in) of torque when securing the MT10 to the host.
- 3. Use safe ESD practices when handling and mounting the MT10.



Top View



3-3. Window Materials

Following are descriptions of three popular window materials:

- 1. Poly-methyl Methacrylic (PMMA)
- 2. Allyl Diglycol Carbonate (ADC)
- 3. Chemically tempered float glass

Cell Cast Acrylic (ASTM: PMMA)

Cell cast Acrylic, or Poly-methyl Methacrylic is fabricated by casting acrylic between two precision sheet of glass. This material has very good optical quality, but is relatively soft and susceptible to attack by chemicals, mechanical stress and UV light. It is strongly recommended to have acrylic hard-coated with Polysiloxane to provide abrasion resistance and protection from environmental factors. Acrylic can be laser-cut into odd shapes and ultrasonically welded.

Cell Cast ADC, Allyl Diglycol Carbonate (ASTM: ADC)

Also known as CR-39[™], ADC, a thermal setting plastic widely used for plastic eyeglasses, has excellent chemical and environmental resistance. It also has an inherently moderate surface hardness and therefore does not require hard-coating. This material cannot be ultrasonically welded.

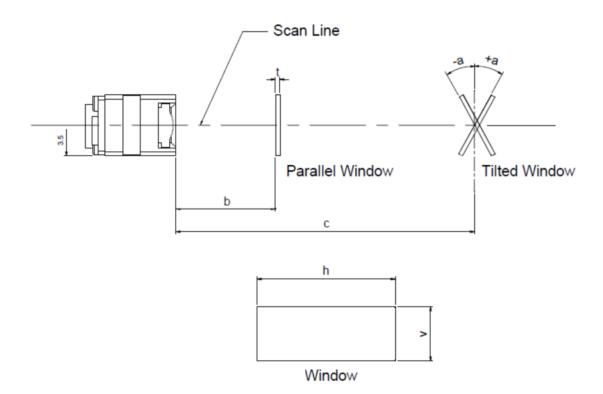
Chemically Tempered Float Glass

Glass is a hard material which provides excellent scratch and abrasion resistance. However, un-annealed glass is brittle. Increased flexibility strength with minimal optical distortion requires chemical tempering. Glass cannot be ultrasonically welded and is difficult to cut into odd shapes.

Property	Description		
Spectral Transmission	85% minimum from 635 to 690 nanometers		
Thickness	< 1 mm		
	Both sides to be anti-reflection coated to provide 1%		
	maximum reflectivity from 635 to 690 nanometers at		
Cooting	nominal window tilt angle. An anti-reflection coating can		
Coating	reduce the light that is reflected back to the host case.		
	Coatings will comply with the hardness adherence		
	requirements of MIL-M-13508.		



3-4. Window Specifications

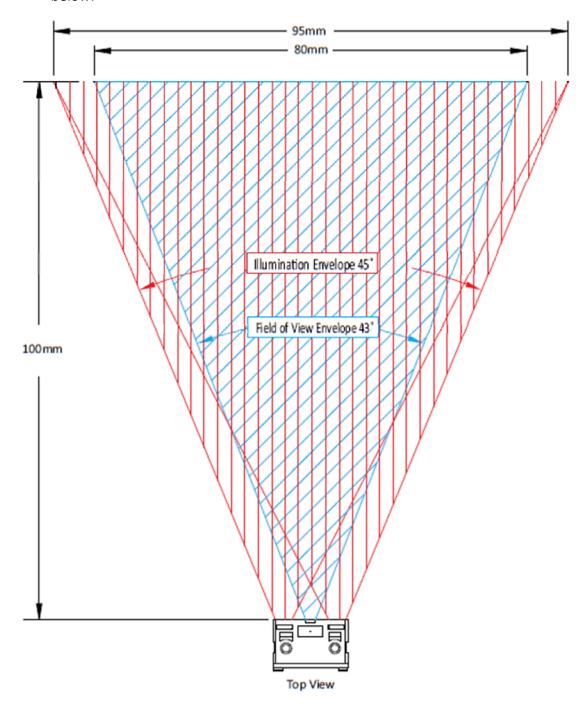


Window Specifications for MT10 Integration					
Distance	Tilt Angle (a)		Minimum Window Size		
Distance Till Ai		gie (a)	Horizontal (h)	Vertical (v)	Thickness (t)
< 0.5mm (b)	0	0	18 mm	5.5 mm	
10 mm (c)	+20°~	-20°~	32 mm	6 mm	< 1 mm
20 mm (c)	+17°~	-17°~	48 mm	6.5 mm	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \
30 mm (c)	+15°~	-15°~	64 mm	7 mm	



MT10 Linear Image Scan Engine, Integration Guide, V1.6

The window size must increase as it is moved away from MT10 and should be sized to accommodate the field of view and illumination envelopes shown below:





3-5. Window Care

In the aspect of window, the performance of MT10 will be reduced due to any kind of scratch. Thus, reducing the damage of window, there are few things have to be noticed.

- 1. Avoid touching the window as much as possible.
- 2. When cleaning the window surface, please use non-abrasive cleaning cloth, and then gently wipe the host window with the cloth that is already sprayed with glass cleaner.

4. REGULATIONS

The MT10 scan engine conforms to the following regulations:

- 1. Electromagnetic Compliance CE EN55022, EN55024
- 2. Electromagnetic Interference FCC Part15 Subpart B (Class B)
- 3. Photobiological Safety IEC 62471 (Exempt Group)
- 4. Environmental Regulations RoHS 2.0, WEEE



5. DEVELOPMENT KIT

MARSON MB100 Demo Kit (P/N: 11A0-9801A20) enables the development of products and systems using the MT10 on the MS Windows OS platform. Besides the Multi I/O board (P/N: 2006-1007X00), the MB100 Demo Kit provides the software and hardware tools required for testing the MT10 applications before integrating it into the host device. Please contact your sales representative for ordering information.

MB100 Multi I/O Board (P/N: 2006-1007X00)

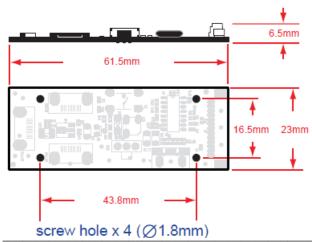


MB100 Demo Kit Accessories

O: Supported X: Not Supported

Cable	Interface	RS232	USB HID	USB VCP
External Y-cable		0	0	0
(P/N: 7090-1583A00)		0	0	O
Internal Y-cable				
(P/N: 5300-1315X00)		0	0	0
Micro USB Cable		V		•
(P/N: 7005-9892A50)		Х	0	0

Due to the advantage of its small size, MB100 Multi I/O board is also suitable for being installed inside the host system, as an interface board connecting MT10 to the host device.





6. SLEEP (IDLE) MODE

The **Sleep (Idle) Mode** is disabled by default. To enable **Sleep (Idle) Mode**, simply follow below instruction to configure the "Pre-Idle Time", or the period of inactivity before MT10 enters Sleep (Idle) Mode, as appropriate.

A. Standard Mode

Firmware version: SM3-d-x.xx (MT10 P/N: 110P-A000000)

Steps:

- 1. Scan SET MINUTE [.B030\$] or SET SECOND [.B029\$]
- 2. Scan two digit from the numeric barcode table below.
- 3. Scan SET MINUTE [.B030\$] or SET SECOND [.B029\$]

Notes:

Pre-Idle Time - Min: 10 sec, Max: 60 min & 60 sec



SET MINUTE (Range: 00 ~ 60)



1	6	
2	7	
3	8	
4	9	
5	0	



B. Command Mode

Firmware version: SM3-d-x.xx.CMD (MT10 P/N: 110P-4000000)

Property	Option	Remark
Sleep (Idle) Mode	0 Off	Default : Off
{MC11WT 1 }	1 On	When enabled, scanner will automatically enter
		Sleep Mode after a period of inactivity(Sleep Mode
		timeout).
Pre-Idle Time	A number from	Default : 1 minute
{MC11WT, 1 , 0 }	0~60 (Minute)	Sleep Mode timeout(10 sec ~ 60 min & 60 sec), the
	A number from	period of inactivity before the scanner enters Sleep
	0~60 (Second)	Mode.

Steps:

- 1. Send {MC11WT1} & {MC11WT,1,0} to the MT10 if you want to enable **Sleep (Idle) Mode** and set Pre-Idle Time as 1 minute.
- 2. The MT10 will return {MC11,OK} and {MC11,1,1,0} respectively as confirmation.
- 3. If you want above settings to be saved permanently in Flash ROM, send {MCMDWT1} to the MT10. Otherwise MT10 will be reset to default after wake up from sleep.

Notes:

Curly braces "{ }" must be included at both ends of each command.

7. PARAMETER SETUP

You can set up your MT10 using one of the following methods:

1. Standard Mode (F/W ver.: SM3-d-x.xx):

Scan configuration barcodes from the Universal User's Manual, or use Ez Utility[®], both of which are available for download at www.marson.com.tw

2. Command Mode (F/W ver.: SM3-d-x.xx.CMD):

Send software commands from the host, or use BEO®, which is available for download at www.marson.com.tw. Full list of software commands can be found in the Help File of BEO program, on the chapter *Test Window/ Command Operation*.



8. VERSION HISTORY

Rev.	Date	Description	Issued	Checked
1.0	2016.05.09	Preliminary Draft Release	Shaw	Jou
1.1	2016.05.11	Revised D.O.F	Shaw	Jou
1.2	2016.07.06	Revised Electric & Flex Cable Specification	Shaw	Jou
1.3	2016.10.31	Revised Sleep Mode command in Chapter 6	Shaw	Jou
1.4	2017.06.21	Deleted Red Cell-Cast Acrylic Description	Shaw	Hus
1.5	2018.03.06	Revised P/N on page10&24	Shaw	Jou
1.6	2018.03.15	Updated Chapter 1 and 1-1 on MCU. Updated Chapter 6 on Command Mode settings.	Shaw	Jou & Hus

Marson Technology Co., Ltd.

9F., 108-3, Mincyuan Rd., Sindian Dist., New Taipei City, Taiwan

TEL: 886-2-2218-1633 FAX: 886-2-2218-6638

E-mail: info@marson.com.tw Web: www.marsontech.com